

**IN THE SPECIFICATION:**

**Please amend paragraph [0025] as follows:**

First, a left half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PL1 on a left side of the handle holder 19 has a mass of mL1 (hereinafter referred to as "left handle mass mL1"), while the left grip 20 has a mass of mL2 (hereinafter referred to as "left grip mass mL2"). Thus, the left side has a mass of mL3 which is a sum of the left handle mass mL1 and the left grip mass mL2 ( $mL3 = mL1 + mL2$ ). The sum mL3 of the left side has a center of gravity as at GL. The present invention is characterized in that the left grip 20 is mounted to the handle 19 by a screw 24 at only a single mounting portion 25 (see Figs. 5A and 5B) substantially at its center of gravity GL corresponding to the left side mass mL3 which is a sum of the left handle portion mass mL1 and the left grip mass mL2, or at a position proximate thereto.

**Please amend paragraph [0026] as follows:**

Now, a right half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PR1 on a right side of the handle holder 19 has a mass of mR1 (hereinafter referred to as "right handle mass mR1"), while

the right grip 39 has a mass of  $mR2$  (hereinafter referred to as "right grip mass  $mR2$ "). Thus, the right side has a mass of  $mR3$  which is a sum of the right handle mass  $mR1$  and the right grip mass  $mR2$  ( $mR3 = mR1 + mR2$ ). The sum  $mR3$  of the right side has a center of gravity as at GR. The present invention is characterized in that the right grip 30 is mounted to the handle 18 by a screw 24 at ~~only~~ a ~~single~~ mounting portion 25 substantially at its center of gravity GR corresponding to the right side mass  $mR3$  which is a sum of the right handle portion mass  $mR1$  and the right grip mass  $mR2$ , or at a position proximate thereto.